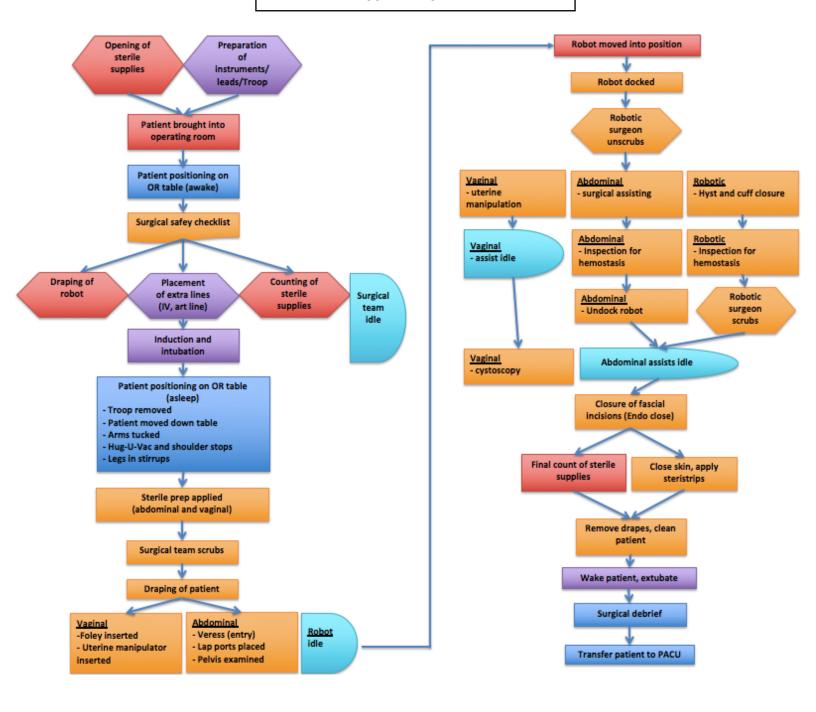
Robotic OR Process Map

CURRENT STATE





Robotic OR Process Map

IDEAL STATE

